

FIG. 1

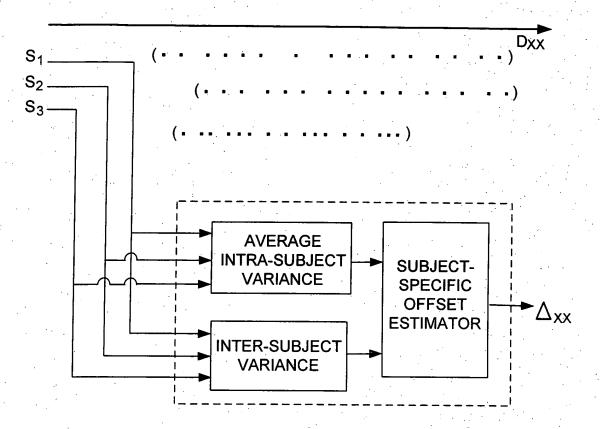
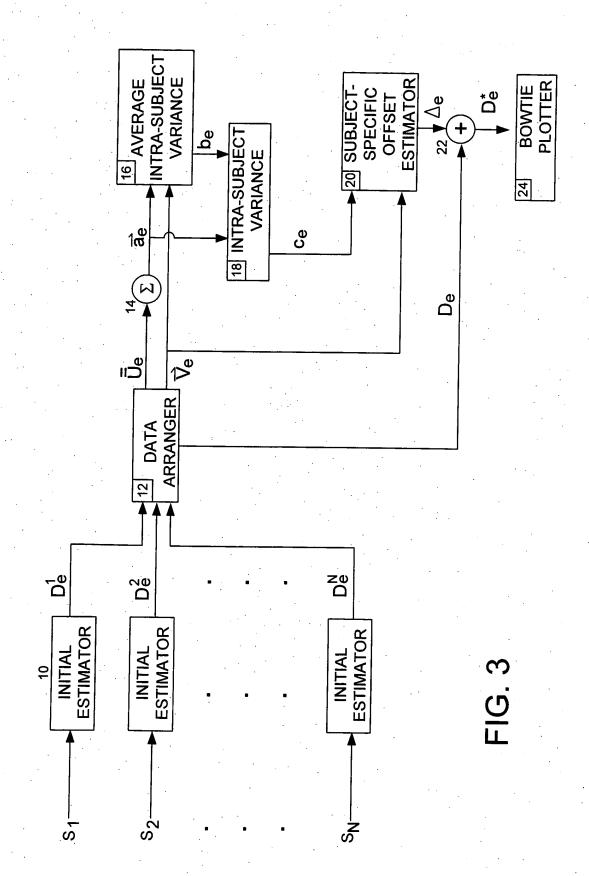


FIG. 2



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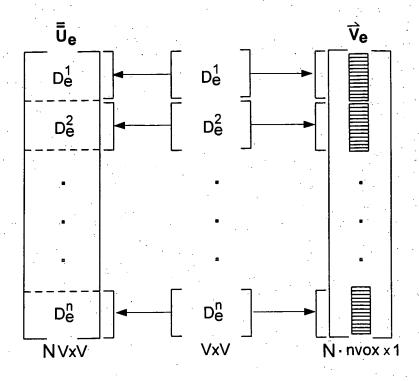
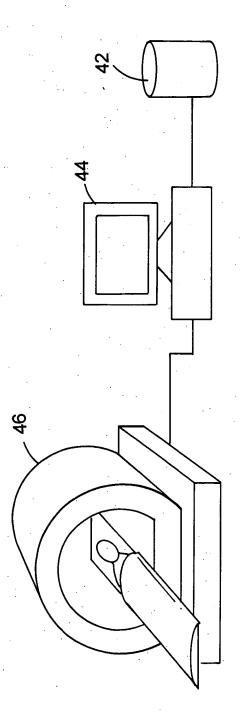


FIG. 4

INTER-SUBJECT COHERENCE IN DT-MRI

$$\begin{array}{l} e = 0 \\ \text{while } e \leq 6 \\ \left\{e = e + 1 \right. \\ \vec{a}_e = \overline{u}_e \cdot \vec{1}_{nvox} \otimes \vec{a}_e \right\} 28 \\ \vec{b}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e T \ \vec{r}_e}{N(v^2 - 1)}\right) - \vec{b}_e \\ \vec{\delta}_e = \left(\frac{\vec{r}_e$$

FIG. 5



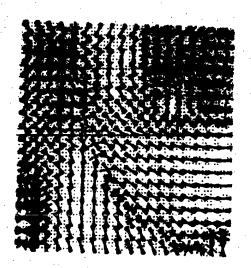


FIG. 7

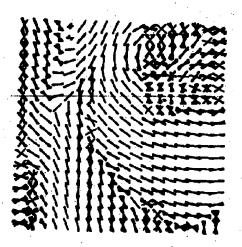


FIG. 8